

# Process Improvement: Steepest Ascent

BIOE 498/598 PJ

Spring 2022

# Process Improvement

Design of Experiments is focused on **process characterization**.

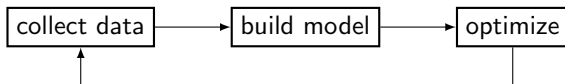
- ▶ Which factors affect the response?
- ▶ How large are the effects?

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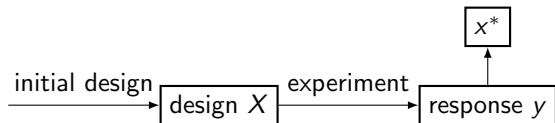
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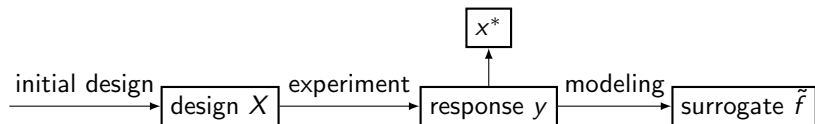
**Process improvement** asks “what factor settings yield the optimal response?”



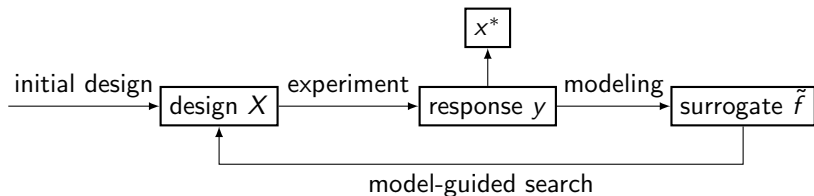
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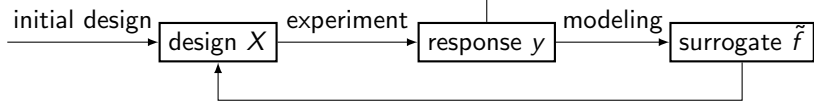
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factorial design  
CCD/BBD  
Latin hypercube  
maximin

linear  
quadratic  
Gaussian process  
neural network



model-guided search

steepest ascent  
direct solution  
L-BFGS  
expected improvement  
rollout

# Process improvement by steepest ascent

- ▶ Rarely are the initial factor ranges optimal. In practice we can be far away.



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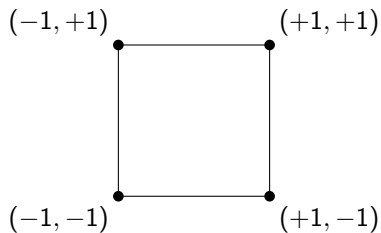
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## Process improvement by steepest ascent

- ▶ Rarely are the initial factor ranges optimal. In practice we can be far away.
- ▶ The **method of steepest ascent** moves us quickly toward regions of better response.
- ▶ The emphasis is on moving quickly using few runs and first order models.

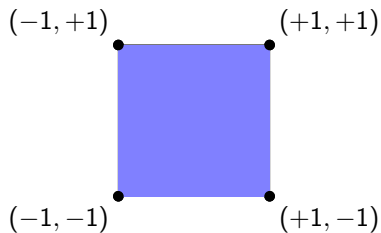
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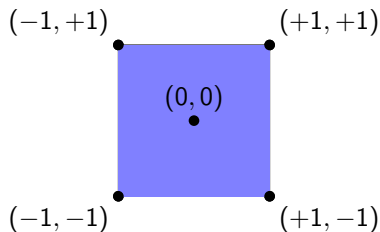
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The origin  $(0, 0)$  in *coded units* is called the **center point**.

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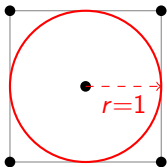
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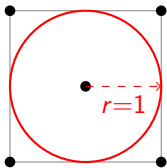
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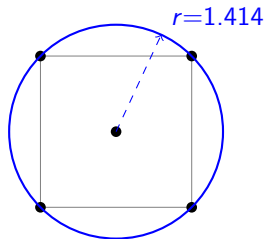
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$r = \sqrt{2} \approx 1.414$  touches the factorial points

## First-order response surfaces

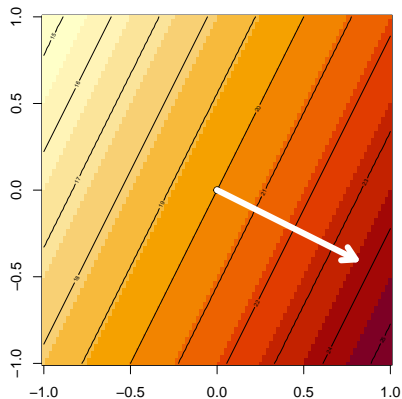
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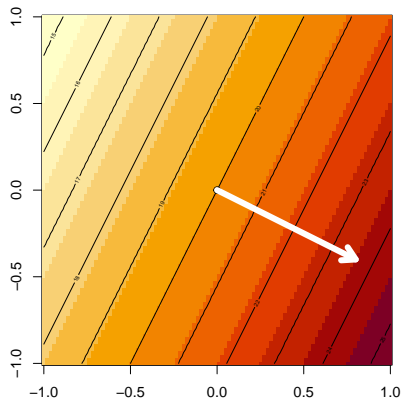
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We want to move “uphill” to improve the response using the **method of steepest ascent**.

If our goal was to minimize the response, we use *steepest descent* by

1. Moving opposite of the uphill direction, or
2. Multiplying the response by  $-1$ .

## Finding the ascent direction for first-order models

Let's compute the partial derivatives along each factor's dimension.

$$\frac{\partial y}{\partial x_1} = \frac{\partial}{\partial x_1} (20 + 3.6x_1 - 1.8x_2) = 3.6$$

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Two things to note:

1. The rate of ascent along each direction is simply the effect size  $\beta_i$ .
2. The rate of change is different for the two dimensions. For every step of unit length along  $x_1$  we must move  $-1.8/3.6 = -1/2$  units along  $x_2$ .

## Standardized step sizes for steepest ascent

Consider the general first-order model

$$y = \beta_0 + \beta_1x_1 + \beta_2x_2 + \cdots + \beta_nx_n$$

1. Find the effect size with the largest **magnitude**. We'll call this  $\beta_j$  and the associated factor  $x_j$ .
2. Choose a step size (in coded units) along this dimension, called  $\Delta x_j$ .
3. For all other dimensions  $i \neq j$ , the step size is

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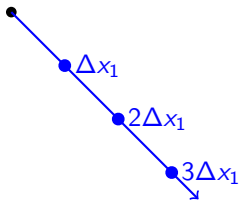
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3.  $\Delta x_2 = \frac{\beta_2}{\beta_1} \Delta x_1 = \frac{-1.8}{3.6}(1) = -0.5$

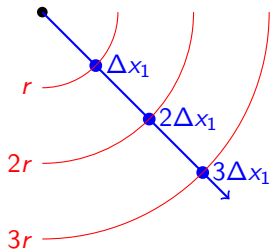
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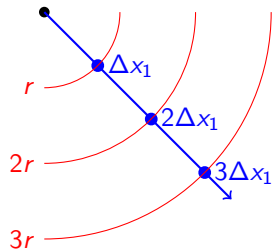
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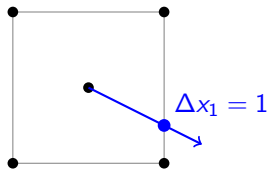


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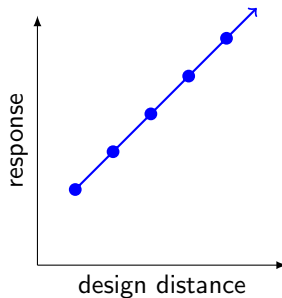


A standardized step of 1 always defines a point on the design space boundary.



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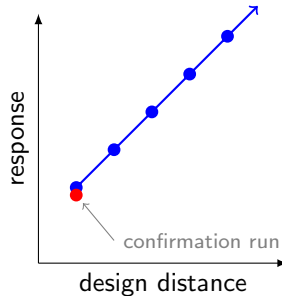
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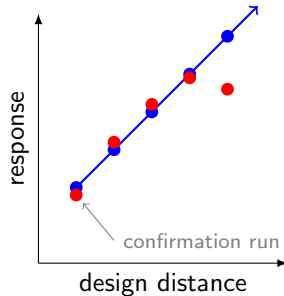
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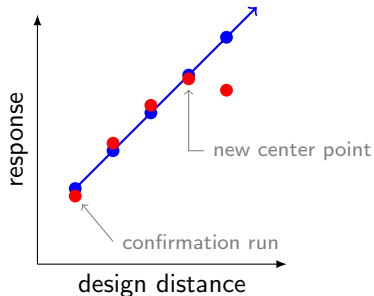
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- ▶ The first run is close to the center to confirm the system behaves as expected.
- ▶ Eventually the actual response will stop increasing.
- ▶ When the response drifts, we use the best response location as the center for a new set of experiments.



## What about interactions?

Models with interactions have **curved** paths of steepest ascent since the gradient changes with  $\mathbf{x}$ .

$$y = \beta_0 + \beta_1 x_1 + \beta_2 x_2 + \beta_{12} x_1 x_2$$

$$\nabla y = \begin{pmatrix} \frac{\partial y}{\partial x_1} \\ \frac{\partial y}{\partial x_2} \end{pmatrix} = \begin{pmatrix} \beta_1 + \beta_{12} x_2 \\ \beta_2 + \beta_{12} x_1 \end{pmatrix}$$

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**However**, in practice we usually ignore the interactions.

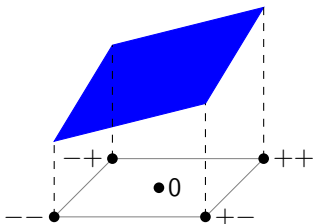
- ▶ The model will often break down before the curvature becomes significant.
- ▶ We rarely have enough runs in the initial design to identify interactions.

## When is a first order model not good enough?

- ▶ The FF designs used for process improvement are usually augmented by **center points** — repeated runs at the design center  $(0, 0)$ .
- ▶ Center points serve two purposes:
  1. Estimate the *pure error* via the standard deviation of the repeated runs.
  2. Test for *lack of fit* to detect curvature.

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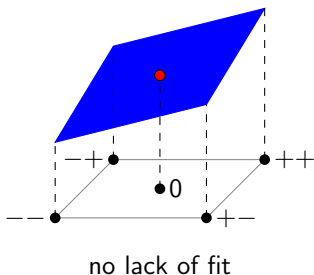
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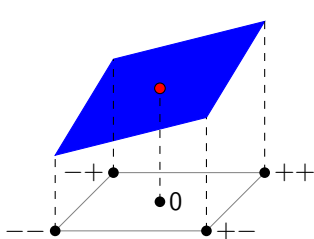
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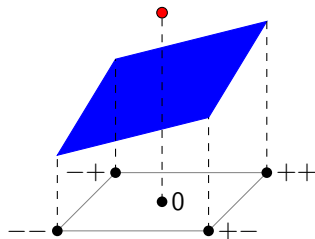


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$$F_{\text{curve}} = \frac{SS_{\text{curve}}/DF(SS_{\text{curve}})}{SS_{\text{error}}/DF(SS_{\text{error}})}$$

## Example: Testing for curvature (Myers 2009)

temp	time	yield
-	-	39.3
-	+	40.0
+	-	40.9
+	+	41.5
0	0	40.3
0	0	40.5
0	0	40.7
0	0	40.2
0	0	40.6



## Example: Testing for curvature (Myers 2009)

1.  $\bar{y}_{\text{fact}} = (39.3 + 40.0 + 40.9 + 41.5)/4 = 40.425$   
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`pf(0.0605, 1, 4, lower.tail=FALSE)`  $\rightarrow p < 0.818$ .

# The steepest ascent method

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4. Go to (1) and repeat using the location of maximum response as the new center point.