# Response Surface Methodology: Central Composite Designs

BIOE 498/598 PJ

Spring 2022

## Surrogate Optimization



rollout

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$$f(x_1, x_2) \approx f|_0 + \frac{\partial f}{\partial x_1}\Big|_0 x_1 + \frac{\partial f}{\partial x_2}\Big|_0 x_2 + \frac{1}{2}\frac{\partial^2 f}{\partial x_1^2}\Big|_0 x_1^2 + \frac{1}{2}\frac{\partial^2 f}{\partial x_2^2}\Big|_0 x_2^2 + \frac{1}{2}\frac{\partial^2 f}{\partial x_1 \partial x_2}\Big|_0 x_1 x_2$$

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- In general we will have k factors and the quadratic approximation will be

$$y = \beta_0 + \sum_{i=1}^k \beta_i x_i + \sum_{i=1}^k \beta_{ii} x_i^2 + \sum_{j=1}^k \sum_{i=1}^{j-1} \beta_{ij} x_i x_j.$$

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► This model has 1 + 2k + k(k - 1)/2 parameters, so RSM designs must have at least this many runs.

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Choosing the correct number of center points in a CCD ensures uniform precision.

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- A CCD with F factorial points is rotatable when  $\alpha = \sqrt[4]{F}$ .

## Rotatable, uniform precision CCDs

factors (k)	2	3	4	5	5 - 1	6
factorial points	4	8	16	32	16	64
axial points	4	6	8	10	10	12
center points	5	6	7	10	6	15
axial distance ( $lpha$ )	1.414	1.682	2.000	2.378	2.000	2.828

factors (k)	6 - 1	7	7 - 1	8	8 - 1	8 – 2
factorial points	32	128	64	256	128	64
axial points	12	14	14	16	16	16
center points	9	21	14	28	20	13
axial distance ( $\alpha$ )	2.378	3.364	2.828	4.000	3.364	2.828

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Unlike a 2-level design, the coded units in a CCD have meaning!

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$$\begin{aligned} \mathsf{A} &= \mathsf{center}(\mathsf{A}) + \frac{\mathsf{range}(\mathsf{A})}{2\alpha} [\mathsf{code}] \\ &= -1.1 + \frac{1 - (-3.2)}{2(1.68)} [\mathsf{code}] \end{aligned}$$

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